



Outside Diameter 30mm (Shaft  $\phi$ 4) PCD 22 Economical Voltage output type

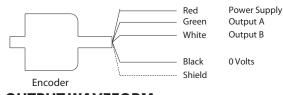
Suitable for General or Industrial Applications

# STANDARD MODELS

Serial Number PPR	<b>CE</b> (30 <i>φ</i> )
60	CE - 60
100	CE - 100
200	CE - 200
250	Discontinued CE - 250
300	CE - 300
360	CE - 360
400	CE - 400
500	CE - 500

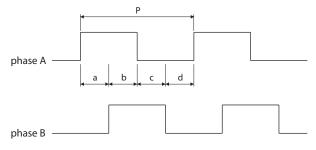
Add " S " at the end of Model No. for 1 signal output (only signal A). ex. CE-100S

## CONNECTIONS

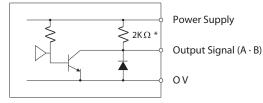


## **OUTPUT WAVEFORM**

clockwise rotation when viewed from the top of the shaft.



## **OUTPUT WIRING**



#### HANDLING GUIDE

- To protect an encoder from any shock or vibration that may be caused by the joining machine, put the center of encoder's shaft and machine's shaft together without aberration and inclination. Use our coupling models for the right joining.
- Be sure to wire the encoder correctly as a wrong wiring may cause the inner circuit breakdown.
- Do not wire the cable parallel with other power lines from the protection against the noise.
- Use a shield wire for the extension of cable.



# **SPECIFICATIONS**

	CE
Power Supply	5 - 12V DC ±5%
Output Signal	Voltage / 90° Quadrature x 2 Signals
Output Voltage	Logic 1 = 4 to 11 VDC (Reduced -1V from Power Supply) Logic 0 = 0.5 VDC or less
Maximum Response	60 KHz
Current Consumption	40 mA maximum
Sink Current	20 mA maximum
Output Impedance	2 Κ Ω
Operating Temperature	-10°C - +70°C
Maximum Speed of	6,0 <b>00 rpm</b>
Shaft Input	
Maximum of Inertia of Shaft	2g-cm <sup>2</sup> Maximum
Starting Torque	10gf-cm Maximum
Angular Speed	1 x 10 <sup>5</sup> rad / sec <sup>2</sup>
Maximum Radial Loading	1 Kg
Maximum Thrust Loading	0.5 Kg
Vibration	10Hz to 50Hz · 1.5mm·2h
Shock	50 G / 11 ms
Weight (Approximately)	100 grams
	Output Signal   Output Voltage   Maximum Response   Current Consumption   Sink Current   Output Impedance   Operating Temperature   Maximum Speed of   Shaft Input   Maximum of Inertia   of Shaft   Starting Torque   Angular Speed   Maximum Thrust Loading   Vibration   Shock

· Signal A and Signal B are 90° quadrature

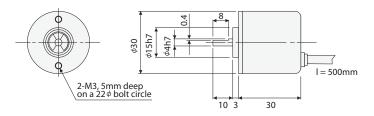
$$\cdot P = \frac{1}{PPR}$$

· Accuracy

$$a \cdot b \cdot c \cdot d = \frac{P}{4} \pm \frac{P}{8}$$

$$h = P \pm \frac{P}{2}$$

#### DIMENSIONS



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